GRAPE-DR and Next-Generation GRAPE

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Talk structure

- Short history of GRAPE
  - GRAPE machines
- GRAPE-DR
  - Architecture
  - Comparison with other architecture
  - Development status
- Next-Generation GRAPE
  - Future of accelerators
Short history of GRAPE

- Basic concept
- GRAPE-1 through 6
- Software Perspective
Basic concept (As of 1988)

- With $N$-body simulation, almost all calculation goes to the calculation of particle-particle interaction.
- This is true even for schemes like Barnes-Hut treecode or FMM.
- A simple hardware which calculates the particle-particle interaction can accelerate overall calculation.

Accelerator-based computing two decades ago
Chikada’s idea (1988)

- Hardwired pipeline for force calculation (similar to Delft DMDP)
- Hybrid Architecture (things other than force calculation done elsewhere)
GRAPE-1 to GRAPE-6

GRAPE-1: 1989, 308Mflops
GRAPE-4: 1995, 1.08Tflops
GRAPE-6: 2002, 64Tflops
Since 1995 (GRAPE-4), GRAPE has been faster than general-purpose computers. Development cost was around 1/100.
Software development for GRAPE

GRAPE software library provides several basic functions to use GRAPE hardware.

- Sends particles to GRAPE board memory
- Sends positions to calculate the force and start calculation
- get the calculated force (asynchronous)

User application programs use these functions. Algorithm modifications (on program) are necessary to reduce communication and increase the degree of parallelism.
Analogy to BLAS

<table>
<thead>
<tr>
<th>Level</th>
<th>BLAS</th>
<th>Calc:Comm</th>
<th>Gravity</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>c=c−a*s</td>
<td>1:1</td>
<td>$f_{ij} = f(x_i, x_j)$ 1:1</td>
</tr>
<tr>
<td>1</td>
<td>AXPY</td>
<td>$N : N$</td>
<td>$f_i = \sum_j f(x_i, x_j)$ $N : N$</td>
</tr>
<tr>
<td>2</td>
<td>GEMV</td>
<td>$N^2 : N^2$</td>
<td>$f_i = \sum_j f(x_i, x_j)$ $N^2 : N$</td>
</tr>
<tr>
<td>3</td>
<td>GEMM</td>
<td>$N^3 : N^2$</td>
<td>$f_{k,i} = \sum_j f(x_{k,i}, x_{k,j})$ $N^2 : N$</td>
</tr>
</tbody>
</table>

- Calc $\gg$ Comm essential for accelerator
- Level-3 (matrix-matrix) essential for BLAS
- Level-2 like (vector-vector) enough for gravity
- Treecode and/or short-range force might need Level-3 like API.
Porting issues

- Libraries for GRAPE-4 and 6 (for example) are not compatible

- Even so, porting was not so hard. The calls to GRAPE libraries are limited to a fairly small number of places in an entire application code.

- Backporting the GRAPE-oriented code to CPU-only code is easy, and allows very efficient use of SIMD features.

- In principle the same for GPGPU.
Real-World issues with “Porting”
— Mostly on GPGPU....

- Getting something run on GPU is not difficult
- Getting a good performance number compared with non-optimized, single-core x86 performance is not so hard.
Quotes

From: Twelve Ways to Fool the Masses When Giving Performance Results on Accelerators Parallel Computers (D. H. Bailey, 1991)

1. Quote only 32-bit performance results, not 64-bit results.
2. Present performance figures for an inner kernel, and then represent these figures as the performance of the entire application.
6. Compare your results against scalar, unoptimized code on Xeons Crays.
7. When direct run time comparisons are required, compare with an old code on an obsolete system.
8. If MFLOPS rates must be quoted, base the operation count on the parallel implementation, not on the best sequential implementation.
12. If all else fails, show pretty pictures and animated videos, and don’t talk about performance.

History repeats itself — Karl Marx
Real-World issues with “Porting” continued

- Making it faster than 10-year-old GRAPE or highly-optimized code on x86 (using SSE/SSE2) is **VERY, VERY HARD** (you need Keigo...)

- These are *mostly* software issues

- Some of the most serious ones are limitations in the architecture (lack of good reduction operation over processors etc)

I’ll return to this issue later.
“Problem” with GRAPE approach

- Chip development cost becomes too high.

<table>
<thead>
<tr>
<th>Year</th>
<th>Machine</th>
<th>Chip initial cost</th>
<th>process</th>
</tr>
</thead>
<tbody>
<tr>
<td>1992</td>
<td>GRAPE-4</td>
<td>200K$</td>
<td>1μm</td>
</tr>
<tr>
<td>1997</td>
<td>GRAPE-6</td>
<td>1M$</td>
<td>250nm</td>
</tr>
<tr>
<td>2004</td>
<td>GRAPE-DR</td>
<td>4M$</td>
<td>90nm</td>
</tr>
<tr>
<td>2010?</td>
<td>GDR2?</td>
<td>&gt; 10M$</td>
<td>45nm?</td>
</tr>
</tbody>
</table>

Initial cost should be 1/4 or less of the total budget. How we can continue?
Next-Generation GRAPE — GRAPE-DR

- Planned peak speed: peak 2 Pflops SP/1Pflops DP
- New architecture — wider application range than previous GRAPEs
- primarily to get funded
- No force pipeline. SIMD programmable processor
- Completion year: FY 2008-2009
Processor architecture

- Float Mult
- Float add/sub
- Integer ALU
- 32-word registers
- 256-word memory
- communication port
Chip architecture

- 32 PEs organized to “broadcast block” (BB)
- BB has shared memory. Various reduction operation can be applied to the output from BBs using reduction tree.
- Input data is broadcasted to all BBs.
- “Solved” data movement problem: Very small number of long wires and off-chip IO.
Computation Model

Parallel evaluation of

\[ R_i = \sum_j f(x_i, y_j) \]

- parallel over both \( i \) and \( j \) (Level-2 gravity)
- \( y_j \) may be omitted (trivial parallelism)
- \( S_{i,j} = \sum_k f(x_{i,k}, y_{k,j}) \) also possible (Level-3 BLAS)
The Chip

Sample chip delivered May 2006
90nm TSMC, Worst case 65W@500MHz
PE Layout

Black: Local Memory
Red: Reg. File
Orange: FMUL
Green: FADD
Blue: IALU

0.7mm by 0.7mm
800K transistors
0.13W@500MHz
1Gflops/512Mflops peak (SP/DP)
Chip layout

- 16 blocks with 32 PEs each
- Shared memory within blocks
- 18mm by 18mm chip size
Processor board

- PCIe x16 (Gen 1) interface
- Altera Arria GX as DRAM controller/communication interface
- Around 200W power consumption
- Not quite running at 500MHz yet... (FPGA design not optimized yet)
- 900Gflops DP peak (450MHz clock)
- Available from K&F Computing Research
GRAPE-DR cluster system
GRAPE-DR cluster system

- 128-node, 128-card system (105TF theoretical peak @ 400MHz)
- Linpack measured: 24 Tflops@400MHz (still lots of tunings necessary....)
- Gravity code: 340Gflops/chip, working
- Host computer: Intel Core i7+X58 chipset, 12GB memory
- network: x4 DDR Infiniband
- plan to expand to 384-node system RSN. (Cables and switches...)
Software Environment

- Kernel libraries
  - DGEMM
    * BLAS, LAPACK
  - Particle-Particle interaction

- Assembly Language

- HLL, OpenMP-like interface

Idea based on PGDL (Hamada, Nakasato)
— pipeline generator for FPGA
Machine code

108-bit horizontal microcode
HLL example

Nakasato (2008), based on LLVM.

VARI xi, yi, zi;
VARJ xj, yj, zj, mj;
VARF fx, fy, fz;
dx=xi-xj;
dy=yi-yj;
dz=zi-zj;
r2= dx*dx+dy*dy+dz*dz;
rintv = rsqrt(r2);
mr3inv = rinv*rinv*rinv*mj;
fx+= mr3inv*dx;
fy+= mr3inv*dy;
fz+= mr3inv*dz;
Driver functions

Generated from the description in the previous slide

```c
int SING_send_j_particle(struct grape_j_particle_struct *jp,
                          int index_in_EM);
int SING_send_i_particle(struct grape_i_particle_struct *ip,
                          int n);
int SING_get_result(struct grape_result_struct *rp);
void SING_grape_init();
int SING_grape_run(int n);
```
Interface struct

```c
struct grape_j_particle_struct{
    double xj;
    double yj;
    double zj;
    double mj;
};
struct grape_i_particle_struct{
    double xi;
    double yi;
    double zi;
};
struct grape_result_struct{
    double fx;
    double fy;
    double fz;
};
```
DGEMM kernel in assembly language (part of)

```assembly
## even loop
bm b10 $lr0v
bm b11 $lr8v

dmul0 $lr0 $lm0v ; bm $lr32v c0 0 ; rrn fadd c0 256 flt72to64

dmul1 $lr0 $lm0v ; upassa $fb $t $t ; idp 0

dmul0 $lr0 $lm256v ; faddAB $fb $ti $lr48v ; bm $lr40v c1 0

dmul1 $lr0 $lm256v ; upassa $fb $t $t

dmul0 $lr2 $lm8v ; faddAB $fb $ti $lr56v ; bm $lr32v c2 1

dmul1 $lr2 $lm8v ; faddA $fb $lr48v $t

.....

dmul0 $lr14 $lm504v ; faddA $fb $ti $lr32v ; bm $lr40v c63 31

dmul1 $lr14 $lm504v ; faddA $fb $lr56v $t

faddA $fb $ti $lr40v

nop

“VLIW”-style
```
Unique feature as parallel language

- Only the inner kernel is specified
- Communication and data distribution are taken care by hardware and library. User-written software does not need to care about.
OpenMP-like compiler

Goose compiler (Kawai 2009)

```c
#pragma goose parallel for icnt(i) jcnt(j) res (a[i][0..2])
    for (i = 0; i < ni; i++) {
        for (j = 0; j < nj; j++) {
            double r2 = eps2[i];
            for (k = 0; k < 3; k++) dx[k] = x[j][k] - x[i][k];
            for (k = 0; k < 3; k++) r2 += dx[k]*dx[k];
            rinv = rsqrt(r2);
            mf = m[j]*rinv*rinv*rinv*rinv;
            for (k = 0; k < 3; k++) a[i][k] += mf * dx[k];
        }
    }
```

Translated to assembly language and API calls.
Performance and Tuning example

- HPL (LU-decomposition)
- Gravity

Based on the work by H. Koike (Thesis work)
LU-decomposition

DGEMM performance

M=N, K=2048, 640 Gflops  450 Gflops

FASTEST single-chip and single-card performance on
the planet!  (HD5870/5970 will be faster...)
DGEMM tuning

Key to high performance: Overlapping communication and Calculation

- PE kernel calculates \( C(8,2) = A(32,8) \times B(8,2) \)
- 512 PEs calculate \( C(256,2) = A(512,256) \times B(512,2) \)

- Next \( B \) sent to chip while calculation
- Previous \( C \) sent to host while calculation
- Next \( A \) sent from host to GDR card while calculation

Everything other than the transfer of \( B \) from host to GDR card is hidden.
LU-decomposition performance

Speed in Gflops as function of Matrix size
430 Gflops (54% of theoretical peak) for N=50K
LU-decomposition tuning

- Almost everything mentioned in Kathy Yelick’s talk
  - except for the concurrent use of CPU and GDR (we use GDR for column factorization as well...)
  - right-looking form
  - TRSM converted to GEMM
  - use row-major order for fast $O(N^2)$ operations

- Several other “new” techniques
  - Transpose matrix during recursive column decomposition
  - Use recursive scheme for TRSM (calculation of $L^{-1}$)

3 weeks to develop the code from scratch
HPL (parallel LU) tuning

- Everything done for single-node LU-decomposition
- Both column- and row-wise communication hidden
- TRSM further modified: calculate $UT^{-1}$ instead of $T^{-1}U$
- More or less working, tuning still necessary

Two months for coding and debugging so far.

N=30K, single node: 240 Gflops
N=60K, 4 nodes: 984 Gflops
(Super-linear because of partial hiding of panel factorization)
Gravity kernel performance

(Performance of individual timestep code not much different)

Assembly code (which I wrote) is not very optimized yet... Should reach at least 600 Gflops after rewrite.
Comparison with GPGPU

Pros:

- Significantly better silicon usage
  512 PEs with 90nm
  40% of the peak DP speed of HD5870 with 1/2 clock and 1/5 transistors

- Designed for scientific applications
  reduction, small communication overhead, etc

Cons:

- Higher cost per silicon area...
  (small production quantity)

- Longer product cycle... 5 years vs 1 year

Good implementations of $N$-body code on GPGPU are there (Hamada, Nitadori, ...)
GPGPU performance for $N$-body simulation

- Impressive for a trivial $N^2$ code with shared timestep (x100 performance!!) — actually x10 compared to a good SSE code.

- $\sim$ x5 for production-level algorithms (tree or individual timestep), $\sim$ x3 or less for the same price, even when you buy GTX295 cards and not Tesla and after Keigo developed new algorithms (without him x2 or less).
GPGPU tuning difficulties

- huge overhead for DMA and starting threads (much longer than MPI communication latency with IB)
- lack of low-latency communication between threads

GRAPE and GRAPE-DR solution

- PIO for sending data from host to GDR
- single PIO write stars calculation
- hardware support for broadcast and reduction

Near-peak performance with minimal bandwidth for both on-board memory and host.
Next-Generation GRAPE

Question:
Any reason to continue hardware development?

- GPUs are fast, and getting faster
- FPGAs are also growing in size and speed
- Custom ASICs practically impossible to make
Next-Generation GRAPE

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Answer?

- GPU speed improvement might slow down
- FPGAs are becoming far too expensive
- Power consumption might become most critical
- Somewhat cheaper way to make custom chips
GPU speed improvement slowing down?

Clear “slowing down” after 2006 (after G80)

Reason: shift to more general-purpose architecture

Discrete GPU market is eaten up by unified chipsets and unified CPU+GPU

But: HPC market is not large enough to support complex chip development
Structured ASIC

- Something between FPGA and ASIC
- From FPGA side: By using one or few masks for wiring, reduce the die size and power consumption by a factor of 3-4.
- eASIC: 90nm (Fujitsu) and 45nm (Chartered) products.
- 45nm: up to 20M gates, 700MHz clock. 1/10 in size and 1/2 in the clock speed compared to ASIC. (1/3 in per-chip price)
- 1/100 initial cost
GRAPEs with eASIC

- Completed an experimental design of a programmable processor for quadruple-precision arithmetic. 6PEs in nominal 2.5Mgates.
- Started designing low-accuracy GRAPE hardware with 7.4Mgates chip.

Summary of planned specs:

- around 8-bit relative precision
- support for quadrupole moment in hardware
- 100-200 pipelines, 300MHz, 2-4Tflops/chip
- small power consumption: single PCIe card can house 4 chips (10 Tflops, 50W in total)
Will this be competitive?

Rule of thumb for a special-purpose computer project:

Price-performance should be more than 100 times better at the beginning of the project

— x 10 for 5 year development time
— x 10 for 5 year lifetime

Compared to CPU: Okay
Compared to GPU: ???
Will this be competitive?

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Will GPUs 10 years from now 100 times faster than today?
Summary

- GRAPE-DR, with programmable processors, will have wider application range than traditional GRAPEs.
- Small cluster of GDR system is now up and running
- Peak speed of a card with 4 chips is 800 Gflops (DP).
- DGEMM performance 640 Gflops, LU decomposition $> 400$Gflops
- Currently, 128-card, 512-chip system is up and running
- We might return to custom design with structured ASIC
Further reading...

http://www.scidacreview.org/0902/html/hardware.html

HARDWARE

Specialized Hardware for Supercomputing

What kind of computer do you imagine when you hear the terms "supercomputing" or "high-performance computing?" A Cray XT3/4/5? An IBM BlueGene? Or a number of rack-mounted IBM/Intel/AMD servers with Infiniband or some other fast network? Certainly, these machines do many large simulations, and from such simulations you can easily find numerous beautiful computer graphics. However, these big machines are not the only way to do large scientific calculations. The GRAPE and GRAPE-DR hardware (figures 1 and 2), developed at the Center for Computational Astrophysics, National Astronomical Observatory of Japan, are alternatives to typical supercomputing architecture.

Transistor Usage and Power Consumption

Accelerator hardware is one alternative to the most widely used supercomputer architectures. The latest example is the IBM Roadrunner system ("Science-Based Prediction at LANL" SciDAC Review 4, Summer 2007, p33), which started operation in June 2006. It consists of approximately 13,000 Cell BE processors, originally developed for the Sony PS3 game console, with double-precision enhancement (PowerXCell 8i). Two Cell processors are mounted on a blade, and two blades are connected to a dual-socket, dual-core Opteron blade through a...